

# Multiple interacting directed walks

ANZAMP Annual Meeting

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# Introduction

- ▶ (Multiple) directed walks can be considered as idealised models of polymers in a solution
- ▶ At the inaugural ANZAMP meeting, we featured a model of two interacting walks near an attractive surface
- ▶ Review the results, including some new ones
- ▶ Insights gained for solving models of  $n > 2$  interacting walks

# What's new

- ▶ Publication (JPhysA): *An exact solution of two friendly interacting directed walks near a sticky wall* - to appear soon
- ▶ Exact solution
- ▶ Polished phase diagram

# Allowed walks

Consider **two directed walks** along the square lattice.  
Let  $\Omega$  be the class of allowed configurations.

- ▶ both walks begin at  $(0, 0)$ , end on the  $x$ -axis.
- ▶ **directed**: can only take steps in the  $(\pm 1, 0)$  directions.
- ▶ **friendly**: walks can share sites, but cannot cross

# Interaction terms

- ▶ **surface visit step**: weight  $a$
- ▶ **shared site contact**: weight  $c$
- ▶ trivial walk consisting of zero steps has weight 1.

## An example

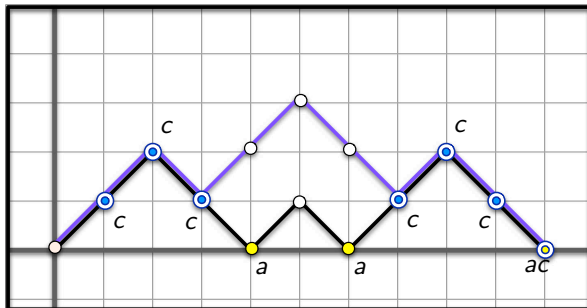


Figure: An allowed configuration of length 10. The overall weight is  $a^3 c^7$ .

# Generating function

We encode all the counting information of every configuration in the **generating function**:

$$G(a, c) \equiv G(a, c; z) = \sum_{\varphi \in \Omega} w(\varphi) z^{|\varphi|}$$

- ▶  $w(\varphi)$  is the weight associated with a given config.
- ▶  $|\varphi|$  is the number of paired steps.
- ▶ e.g. prev. slide,  $w(\varphi) = a^3 c^7$  and  $|\varphi| = 10$ .

# Reduced free energy

With the generating function, we can also determine the reduced free energy  $\psi(a, c)$  of the system.

$$\psi(a, c) = -\log z_s(a, c)$$

where  $z_s(a, c)$  is smallest real and positive singularity of  $G(a, c)$  w.r.t  $z$



# Order parameters

Define suitable order parameters to identify phases of the system.  
The limiting average **surface** contacts

$$\mathcal{A}(a, c) \equiv \lim_{L \rightarrow \infty} \frac{\langle m_a \rangle}{L} = a \frac{\partial \psi}{\partial a}$$

and the limiting average number of **shared sites**

$$\mathcal{C}(a, c) \equiv \lim_{L \rightarrow \infty} \frac{\langle m_c \rangle}{L} = c \frac{\partial \psi}{\partial c}$$

where  $m_a$  and  $m_c$  are the number of surface visits and shared contacts for a given config. resp.

# Phases

- ▶ **free:**  $\mathcal{A} = \mathcal{C} = 0$
- ▶ **adsorbed:** (a-rich)  $\mathcal{A} > 0, \mathcal{C} = 0$
- ▶ **zipped:** (c-rich)  $\mathcal{A} = 0, \mathcal{C} > 0$
- ▶ **adsorbed-zipped:** (ac-rich)  $\mathcal{A} > 0, \mathcal{C} > 0$

## Solution of $G(a, 1)$

For the case where we ignore shared-contact effects, it was found in *Owczarek, Rechnitzer & Wong ('12)* that

$$G(a, 1) = 1 + \sum_{i=1}^{\infty} z^{2i} \sum_{m=1}^i a^m \frac{m(m+1)(m+2)}{(i+1)^2(i+2)(2i-m)} \binom{2i}{i} \binom{2i-k}{i}. \quad (1)$$

## Solution of $G(1, c)$

For the case where we ignore surface-visit effects, we were able to find the exact-solution to the generating function

$$G(1, c; z) = 1 + c^2 z^2 + c^3 (1 + 2z) z^4 \quad (2)$$
$$+ \left\{ \sum_{i=3}^{\infty} z^{2i} \sum_{m=3}^{2i} c^m \sum_{k=3}^m (-1)^{k+1} \frac{k(k-1)(k-2)(2i-k+1)(i-k+2)}{i^2(i-1)^2(i+1)(i-2)} \binom{m}{k} \right.$$
$$\left. \times \binom{2i-k}{i-2} \binom{2i-k-1}{i-3} \right\}.$$

## Solution of $G(a, c)$

Finally, we were able to express  $G(a, c)$  in terms of  $G(a, 1)$  and  $G(1, c)$

$$G(a, c; z) = \frac{1}{(a-1)(c-1)} \left[ 1 + \frac{p_0}{p_1 G(a, 1; z) + p_2 G(1, c; z) + p_3} \right] \quad (3)$$

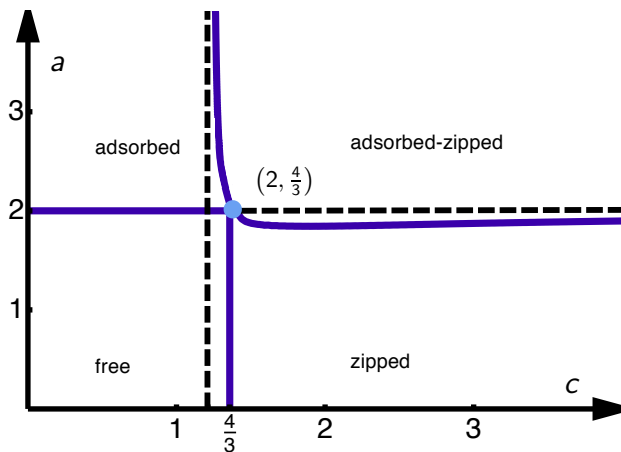
where  $p_i$  are polynomials in  $a, c$  and  $z$ . In particular ...

## Solution of $G(a, c)$ cont'd

$$\begin{aligned}p_0(a, c; z) &= (a - 1)(c - 1)^2(a - c)(ac - c - a) \\ &\quad - (c - 1)(2a - a^2 + 3c - 3ac + a^2c - 2)a^2c^2z^2 - (a - 1)a^2c^4z^4, \\ p_1(a, c; z) &= (a - 1)a^2c^3(1 - a - c + ac)z^4, \\ p_2(a, c; z) &= (a - 1)a(c - 1)^3c^2z^2, \\ p_3(a, c; z) &= (a - 1)(c - 1)^2(a - c) \\ &\quad - a^2(c - 1)c^2[1 + c(a - 2)]z^2 + (a - 1)a^2c^4z^4.\end{aligned}$$

**Key point:** With solutions to  $G(a, 1)$  and  $G(1, c)$  we additionally have solved for  $G(a, c)$ . More on the relation later.

## Phase diagram



**Figure:** All transitions are second-order while the critical point where all boundaries meet (filled circle) occurs when  $a = 2$  and  $c = 4/3$

## $n$ interacting walks

Recall

$$G(a, c; z) = \frac{1}{(a-1)(c-1)} \left[ 1 + \frac{p_0}{p_1 G(a, 1; z) + p_2 G(1, c; z) + p_3} \right]$$

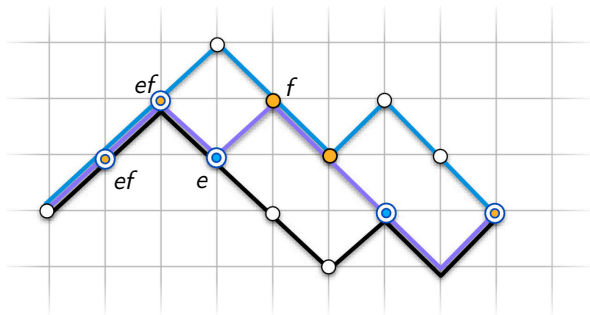
- ▶ Able to isolate interaction effects
- ▶ To our knowledge, such a decomposition previously unseen in the literature
- ▶ Should we expect this kind of decomposition for similar models ( $n > 2$  interacting walks) ?



## $n$ interacting walks cont'd

- ▶ Relation for  $G(a, c)$  obtained analytically, but not very illuminating for understanding general case
- ▶ Ideally, we would like a **combinatorial proof**
- ▶ But as a start, consider the case where  $n = 3$  to see if we can repeat the process used for  $G(a, c)$

## Three walks in bulk



Let  $\Delta$  be comb. class of three directed friendly walks in bulk

$$H(e, f) \equiv H(e, f; z) = \sum_{\varphi \in \Delta} w(\varphi) z^{|\varphi|}$$

## Some notation - coefficient extraction

Treating  $H(e, f)$  as a power series in  $e$ , we have

$$H(e, f) = \sum_{i \geq 0} A_i(f, z)e^i, \quad A_i(f, z) \in \mathbb{Z}[f, z]$$

and we denote the coefficient  $A_i(f, z)$  as

$$[e^i]H(e, f) \equiv A_i(f, z)$$

## Three walks in bulk cont'd

Solving for general  $H(e, f)$  by the exact same process as  $G(a, c)$  has not been possible. But we do know

- ▶ Combinatorial relation:

$$H(1, f) = \frac{-2fz + [e^1]H(e, f)}{f^2z^2} \quad (4)$$

- ▶ We can find  $[e^1]H(e, f)$  using same techniques as for  $G(a, c)$
- ▶ By symmetry, we can also solve for  $H(e, 1)$

## Three walks in bulk cont'd

Most importantly, for the **equal interaction** case (i.e.  $f = e$ ) we have found that

$$H(e, e) = \frac{1}{(e-1)^2} \left[ 1 + \frac{q_0}{q_1 H(e, 1; z) + q_3} \right]$$

where  $q_i$  are polynomials in  $e$  and  $z$ .

- ▶ Closely resembles decomposition for  $G(a, c)$
- ▶ Suggests that we can also relate  $H(e, f)$  in terms of  $H(1, f)$  and  $H(e, 1)$ !

# To do

- ▶ Explicitly solve  $H(1, f)$  and  $H(e, 1)$
- ▶ Find relation for  $H(e, f)$  in terms of  $H(1, f)$  and  $H(e, 1)$  (?)

## Distant future

- ▶ Can we generalize for arbitrary  $n$  interacting directed walks?
- ▶ i.e. relate  $H(e_1, e_2, \dots, e_{n-1})$  to  $H(e_1, 1, 1, \dots, 1)$ ,  $H(1, e_2, 1, \dots, 1)$ ,  
...  $H(1, 1, \dots, e_{n-1})$

Thanks!