

# Superintegrability in a non-conformally-flat space

Jonathan Kress

(Joint work with Ernie Kalnins and Willard Miller)

School of Mathematics and Statistics  
University of New South Wales

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What is a superintegrable system?

Higher Symmetries of the Laplacian

Extending the superintegrable TTW systems to higher dimensions

Superintegrability suggests a non-standard conformally covariant Laplacian

# What is a Superintegrable Systems?

Consider  $H$ , a natural Hamiltonian on a  $2n$ -dimensional phase space

$$H = \sum_{i,j=1}^n g^{ij} p_i p_j + V(x_1, \dots, x_n).$$

$H$  is Liouville **integrable** means there are  $n$  functions of the phase space

$$L_0 = H, L_1, \dots, L_{n-1},$$

that are

- functionally, independent
- globally defined,
- Poisson commuting:  $\{L_i, L_j\} = 0$  for  $i = 0 \dots n-1$ .

$H$  is **superintegrable** means that  $H$  is integrable and additionally there are further functionally independent constants up to a maximum of  $2n-1$ . That is,

$$\{H, L_i\} = 0 \quad \text{for } i = 0 \dots 2n-2.$$

Here consider only constants polynomial in the momenta. Eg, second order constants:

$$L_i = \sum_{j,k=1}^n a_{(i)}^{jk} p_j p_k + W_{(i)}(x_1, \dots, x_n).$$

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# What is a Superintegrable Systems?

- The trajectories can be found algebraically. They must lie on the intersection of the level sets of the  $2n - 1$  constants.
- The Kepler-Coulomb and isotropic oscillator systems are the best known examples.
- For quantum superintegrability momenta and the Poisson brackets replaced by differential operators and the operator commutators.
- Classical and quantum superintegrable systems typically have a Poisson or commutator algebra that closes polynomially.
- Superintegrable systems with all second order symmetries are multi-separable and provide information on special functions.
- Connections with Quasi-Exactly-Solvable systems.

The Hamiltonian

$$H = p_x^2 + p_y^2 + \alpha(x^2 + y^2) + \frac{\beta}{x^2} + \frac{\gamma}{y^2}$$

has two constants that are second order polynomials in the momenta

$$L_1 = p_x^2 + \alpha x^2 + \frac{\beta}{x^2}, \quad L_2 = (xp_y - yp_x)^2 + \beta \frac{y^2}{x^2} + \gamma \frac{x^2}{y^2}.$$

$$\{H, L_1\} = \{H, L_2\} = 0.$$

With  $R = \{L_1, L_2\}$  the Poisson algebra closes quadratically.

$$\{R, L_1\} = 8L_1^2 - 8HL_1 + 16\alpha L_2,$$

$$\{R, L_2\} = -16L_1L_2 + 8HL_2 - 16(\beta + \gamma)L_1 + 16H\beta,$$

$$R^2 = -16L_1^2L_2 + 16HL_1L_2 - 16\alpha L_2^2 - 16(\beta + \gamma)L_2^2 + 32\beta HL_1 \\ - 16\beta H^2 + 16\alpha\beta\gamma.$$

Some examples...

- Oscillators with rational frequency ratios

$$H = \frac{1}{2}(p_x^2 + p_y^2) + \omega_1^2 x^2 + \omega_2^2 y^2, \quad \frac{\omega_1}{\omega_2} \in \mathbb{Q}$$

- Calogero-Moser (Wojciechowski, 1983)

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + \sum_{i < j=1}^n \frac{1}{(x_i - x_j)^2}$$

- Toda lattice (Agrotis, Damianou, Sophocleous, 2005)

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + \sum_{i=1}^{n-1} e^{x_i - x_{i+1}}$$

- A non-separable system (Post and Winternitz, 2011)

$$H = \frac{1}{2}(p_x^2 + p_y^2) + \frac{\alpha y}{x^{2/3}}$$

Homogeneous polynomials in the momenta correspond to symmetric contravariant tensors.

If  $H_0$  and  $L_0$  are the leading terms of  $H$  and  $L$  as polynomials in the momenta, then

$$\{H_0, L_0\} = 0 \quad \Longleftrightarrow \quad [g, K] = 0$$

where  $[ , ]$  is the Schouten bracket and

$$g = g^{ij} \frac{\partial}{\partial x_i} \odot \frac{\partial}{\partial x_j} \quad \text{and} \quad K = a^{i_1 \cdots i_r} \frac{\partial}{\partial x_{i_1}} \odot \cdots \odot \frac{\partial}{\partial x_{i_r}}.$$

$K$  is a second rank (symmetric) Killing tensor.

The leading terms (symbol) of a differential operator symmetry of the (conformal) Laplacian is a (conformal) Killing tensor.

Do all (conformal) Killing tensors correspond to a symmetry of the (conformal) Laplacian?

Tremblay, Turbiner and Winternitz (2009) introduced a family of potentials

$$V_{TTW} = \alpha r^2 + \frac{\beta}{r^2 \cos^2(k\theta)} + \frac{\gamma}{r^2 \sin^2(k\theta)}.$$

For  $k = 1, 2, 3$  these were known systems (Smorodinsky-Winternitz, rational  $BC_2$  model, Wolfes model).

For all  $k \in \mathbb{N}^+$ , Tremblay, Turbiner and Winternitz

- showed that the quantum systems are *exactly solvable* and the classical systems have closed trajectories.
- demonstrated superintegrability for  $k = 1, 2, 3, 4$ .
- conjectured superintegrability for rational  $k$ .

The classical and quantum TTW systems are superintegrable for all positive rational parameter values (KMP 2009, KKM 2010).

These results have been extended to other families, eg

$$H = \cosh^2 \psi \left( p_\psi^2 + p_\varphi^2 + \frac{\alpha}{\cos^2 k\varphi} + \frac{\beta}{\sin^2 k\varphi} + \frac{\gamma}{\sinh^2 \psi} \right).$$

The methods used allow explicit calculation of the symmetry algebra which closes polynomially.

In the following I will describe some extensions to higher dimensions.

The classical TTW Hamiltonian for  $k = 1$  can be written in Cartesian coordinates as

$$H_{TTW} = p_x^2 + p_y^2 + \alpha(x^2 + y^2) + \frac{\beta_1}{x^2} + \frac{\beta_2}{y^2}$$

and in polar coordinates as

$$H_{TTW} = p_r^2 + \alpha r^2 + \frac{1}{r^2} \left( p_\theta^2 + \frac{\beta_1}{\cos^2 \theta} + \frac{\beta_2}{\sin^2 \theta} \right)$$

A natural generalization to 3 dimensions is

$$H = p_x^2 + p_y^2 + p_z^2 + \alpha(x^2 + y^2 + z^2) + \frac{\beta_1}{z^2} + \frac{\beta_2}{x^2} + \frac{\beta_3}{y^2}$$

or in polar coordinates,

$$H = p_r^2 + \alpha r^2 + \frac{1}{r^2} \left( p_{\theta_1}^2 + \frac{\beta_1}{\cos^2 \theta_1} + \frac{1}{\sin^2 \theta_1} \left( p_{\theta_2}^2 + \frac{\beta_2}{\cos^2 \theta_2} + \frac{\beta_3}{\sin^2 \theta_2} \right) \right)$$

This pattern will continue in higher dimensions.

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This pattern will continue in higher dimensions.

The classical TTW Hamiltonian for arbitrary  $k$  is written in polar coordinates as

$$H_{TTW} = p_r^2 + \alpha r^2 + \frac{1}{r^2} \left( p_\theta^2 + \frac{\beta_1}{\cos^2(k\theta)} + \frac{\beta_2}{\sin^2(k\theta)} \right)$$

and so we generalize this as

$$H = p_r^2 + \alpha r^2 + \frac{1}{r^2} \left( p_{\theta_1}^2 + \frac{\beta_1}{\cos^2(k_1\theta_1)} + \frac{1}{\sin^2(k_1\theta_1)} \left( p_{\theta_2}^2 + \frac{\beta_2}{\cos^2(k_2\theta_2)} + \frac{\beta_3}{\sin^2(k_2\theta_2)} \right) \right)$$

and so on to higher dimensions.

Inside each pair of brackets is a constant of the motion.

Such systems are superintegrable.

We now consider a 4-dimensional generalization of the TTW system.

$$\begin{aligned}
 H = L_1 &= p_r^2 + \alpha r^2 + \frac{L_2}{r^2} \\
 L_2 &= p_{\theta_1}^2 + \frac{\beta_1}{\cos^2(k_1\theta_1)} + \frac{L_3}{\sin^2(k_1\theta_1)} \\
 L_3 &= p_{\theta_2}^2 + \frac{\beta_2}{\cos^2(k_2\theta_2)} + \frac{L_4}{\sin^2(k_2\theta_2)} \\
 L_4 &= p_{\theta_3}^2 + \frac{\beta_3}{\cos^2(k_3\theta_3)} + \frac{\beta_4}{\sin^2(k_3\theta_3)}.
 \end{aligned}$$

This system is superintegrable for all positive rational  $k_1$ ,  $k_2$  and  $k_3$ .

The corresponding metric

$$g = e_0 \otimes e_0 + e_1 \otimes e_1 + e_2 \otimes e_2 + e_3 \otimes e_3,$$

$$e_0 = dr, \quad e_1 = r d\theta_1, \quad e_2 = r \sin(k_1 \theta_1) d\theta_2, \quad e_3 = r \sin(k_1 \theta_1) \sin(k_2 \theta_2) d\theta_3.$$

is not conformally flat since

$$W_{abcd} W^{abcd} = \frac{4(k_1^2 - k_2^2)^2}{3r^4 \sin^4(k_1 \theta_1)}.$$

$W_{abcd}$  is the Weyl conformal curvature tensor.

The metric  $g$  is conformally flat if and only if  $k_1^2 = k_2^2$ .

Next, illustrate the superintegrability with  $k_1 = 2, k_2 = k_3 = 1$ . The general case is similar.

As an example, with  $k_1, k_2, k_3 = 2, 1, 1$ , we find two additional quartic and a cubic constant of the motion

$$\begin{aligned}
 L_1'' &= \left( H - \frac{2L_2}{r^2} \right) \frac{\sin(4\theta_1)}{r} p_{\theta_1} p_r \\
 &\quad + \frac{2(L_2 \cos(4\theta_1) + L_3 - \beta_1)}{r^2} p_r^2 - \frac{1}{4}(H^2 - \alpha L_2) \cos(4\theta_1), \\
 L_2'' &= 2(L_3 \cos(2\theta_2) + L_4 - \beta_2) \cot(2\theta_1) \sin(2\theta_2) p_{\theta_1} p_{\theta_2} \\
 &\quad + ((\beta_2 - L_3 - L_4)^2 - 4L_3 L_4) \operatorname{cosec}^2(2\theta_1) \\
 &\quad - \sin^2(2\theta_2) (2L_3 \operatorname{cosec}^2(2\theta_1) + \beta_1 - L_2 - L_3) p_{\theta_2}^2 \\
 L_3'' &= 2(L_4 \cos(2\theta_3) + \beta_4 - \beta_3) \cot(\theta_2) p_{\theta_2} \\
 &\quad - (2L_4 \operatorname{cosec}^2(\theta_2) + \beta_2 - L_3 - L_4) \sin(2\theta_3) p_{\theta_3}
 \end{aligned}$$

Setting  $\alpha = \beta_1 = \beta_2 = \beta_3 = 0$  gives higher rank Killing tensors independent of the rank 2 Killing tensors.

The quantum version has four mutually commuting differential operators,

$$H = \partial_r^2 + \frac{3}{r}\partial_r - \omega^2 r^2 + \frac{L_1}{r^2}$$

$$L_1 = \partial_{\theta_1}^2 + 2k_1 \cot(k_1\theta_1)\partial_{\theta_1} + \frac{\beta_1}{\cos^2(k_1\theta_1)} + \frac{L_2}{\sin^2(k_1\theta_1)}$$

$$L_2 = \partial_{\theta_2}^2 + k_2 \cot(k_2\theta_2)\partial_{\theta_2} + \frac{\beta_2}{\cos^2(k_2\theta_2)} + \frac{L_3}{\sin^2(k_2\theta_2)}$$

$$L_3 = \partial_{\theta_3}^2 + \frac{\beta_3}{\cos^2(k_3\theta_3)} + \frac{\beta_4}{\sin^2(k_3\theta_3)}$$

The Hamiltonian is of the form  $H = \nabla^2 + V_0$  where  $\nabla^2$  is the Laplacian on a four-dimensional manifold with metric

$$g = e_0 \otimes e_0 + e_1 \otimes e_1 + e_2 \otimes e_2 + e_3 \otimes e_3,$$

$$e_0 = dr, \quad e_1 = r d\theta_1, \quad e_2 = r \sin(k_1\theta_1) d\theta_2, \quad e_3 = r \sin(k_1\theta_1) \sin(k_2\theta_2) d\theta_3.$$

The equation  $H\Psi = E\Psi$  is separable in the coordinates  $r, \theta_1, \theta_2, \theta_3$  but for reasons that will be 'explained', we add some extra terms.

$$\begin{aligned}
 H = L_0 &= \partial_r^2 + \frac{3}{r}\partial_r - \omega^2 r^2 + \frac{L_1}{r^2} + \frac{1 - k_1^2}{r^2} \\
 L_1 &= \partial_{\theta_1}^2 + 2k_1 \cot(k_1\theta_1)\partial_{\theta_1} + \frac{\beta_1}{\cos^2(k_1\theta_1)} + \frac{L_2}{\sin^2(k_1\theta_1)} + \frac{k_1^2 - k_2^2}{4\sin^2(k_1\theta_1)} \\
 L_2 &= \partial_{\theta_2}^2 + k_2 \cot(k_2\theta_2)\partial_{\theta_2} + \frac{\beta_2}{\cos^2(k_2\theta_2)} + \frac{L_3}{\sin^2(k_2\theta_2)} \\
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 \end{aligned}$$

$H\Psi = E\Psi$  remains separable with the additional terms.

For the metric  $g$ , the scalar curvature is

$$\mathcal{R} = -\frac{6}{r^2} + k_1^2 \left( \frac{6}{r^2} - \frac{2}{r^2 \sin^2(k_1 \theta_1)} \right) + \frac{2k_2^2}{r^2 \sin^2(k_1 \theta_1)},$$

and with Weyl conformal tensor  $W_{abcd}$ , if we define

$$\mathcal{W} = \sqrt{3 W_{abcd} W^{abcd}} = \frac{2(k_1^2 - k_2^2)}{r^2 \sin^2(k_1 \theta_1)}.$$

then

$$H = \nabla^2 + V_0 - \frac{1}{6}\mathcal{R} - \frac{1}{24}\mathcal{W}.$$

The metric  $g$  is conformally flat if and only if  $k_1^2 = k_2^2$ .

We look for solutions of the form

$$H\Psi = E\Psi, \quad \Psi = \Psi_0(r)\Psi_1(\theta_1)\Psi_2(\theta_2)\Psi_3(\theta_3),$$

and

$$L_3\Psi_3 = \ell_3\Psi_3, \quad L_2\Psi_2\Psi_3 = \ell_2\Psi_2\Psi_3, \quad L_1\Psi_1\Psi_2\Psi_3 = \ell_1\Psi_1\Psi_2\Psi_3.$$

For the angular equations we will find the equation

$$u'' + \left( \frac{\frac{1}{4} - \alpha^2}{\sin^2 y} + \frac{\frac{1}{4} - \beta^2}{\cos^2 y} + (2n + \alpha + \beta + 1)^2 \right) u = 0.$$

which has solution

$$u(y) = (\sin y)^{\alpha + \frac{1}{2}} (\cos y)^{\beta + \frac{1}{2}} P_n^{(\alpha, \beta)}(\cos 2y)$$

where  $P_n^{(\alpha, \beta)}(x)$  is a Jacobi function.

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With the replacements

$$\beta_3 = k_3^2 \left( \frac{1}{4} - a_4^2 \right), \quad \beta_4 = k_3^2 \left( \frac{1}{4} - a_3^2 \right),$$

the separated  $\theta_3$  equation is

$$L_3 \Psi_3(\theta_3) = \Psi_3''(\theta_3) + \left( \frac{k_3^2 \left( \frac{1}{4} - a_4^2 \right)}{\cos^2(k_3 \theta_3)} + \frac{k_3^2 \left( \frac{1}{4} - a_3^2 \right)}{\sin^2(k_3 \theta_3)} \right) \Psi_3(\theta_3) = \ell_3 \Psi_3(\theta_3)$$

which has solutions

$$\Psi_{3,n_3}^{a_3,a_4}(\theta_3) = (\sin(k_3 \theta_3))^{a_3 + \frac{1}{2}} (\cos(k_3 \theta_3))^{a_4 + \frac{1}{2}} P_{n_3}^{(a_3,a_4)}(\cos(2k_3 \theta_3))$$

and eigenvalues

$$L_3 \Psi_{3,n_3}^{a_3,a_4}(\theta_3) = \ell_3 \Psi_{3,n_3}^{a_3,a_4}(\theta_3), \quad \ell_3 = -k_3^2 (2n_3 + a_3 + a_4 + 1)^2.$$

The separated  $\theta_2$  equation  $L_2\Psi_2(\theta_2) = \ell_2\Psi_2(\theta_2)$  is

$$\Psi_2''(\theta_2) + k_2 \cot(k_2\theta_2)\Psi_2'(\theta_2) + \left( \frac{\beta_2}{\cos^2(k_2\theta_2)} + \frac{\ell_3}{\sin^2(k_2\theta_2)} \right) \Psi_2(\theta_2) = \ell_2\Psi_2(\theta_2)$$

which we transform with

$$\Psi_2(\theta_2) = (\sin(k_2\theta_2))^{-\frac{1}{2}} \psi_2(\theta_2)$$

to absorb the first derivative term to give

$$\psi_2''(\theta_2) + \left( \frac{\beta_2}{\cos^2(k_2\theta_2)} + \frac{\ell_3 + \frac{1}{4}k_2^2}{\sin^2(k_2\theta_2)} + \frac{1}{4}k_2^2 - \ell_2 \right) \psi_2(\theta_2) = 0$$

and we make the replacements

$$\beta_2 = k_2^2 \left( \frac{1}{4} - a_2^2 \right), \quad \ell_3 + \frac{1}{4}k_2^2 = k_2^2 \left( \frac{1}{4} - A_2^2 \right).$$

$$\ell_3 = -k_3^2(2n_3 + a_3 + a_4 + 1)^2 \quad \Rightarrow \quad A_2 = \frac{k_3}{k_2}(2n_3 + a_3 + a_4 + 1)$$

The separated  $\theta_2$  equation becomes

$$\psi_2''(\theta_2) + \left( \frac{k_2^2 \left( \frac{1}{4} - a_2^2 \right)}{\cos^2(k_2 \theta_2)} + \frac{k_2^2 \left( \frac{1}{4} - A_2^2 \right)}{\sin^2(k_2 \theta_2)} + \frac{k_2^2}{4} - \ell_2 \right) \psi_2(\theta_2) = 0$$

where

$$\frac{k_2^2}{4} - \ell_2 = k_2^2 (2n_2 + a_2 + A_2 + 1)^2$$

and has solution

$$\Psi_{2,n_2}^{A_2,a_2}(\theta_2) = (\sin(k_2 \theta_2))^{A_2} (\cos(k_2 \theta_2))^{a_2 + \frac{1}{2}} P_{n_2}^{(A_2, a_2)}(\cos(2k_2 \theta_2)).$$

The separated  $\theta_1$  equation  $L_1\Psi_1(\theta_1) = \ell_1\Psi_1(\theta_1)$  is

$$\Psi_1''(\theta_1) + 2k_1 \cot(k_1\theta_1)\Psi_1'(\theta_1) + \left( \frac{\beta_1}{\cos^2(k_1\theta_1)} + \frac{\ell_2 + \frac{1}{4}(k_1^2 - k_2^2)}{\sin^2(k_1\theta_1)} \right) \Psi_1(\theta_1) = \ell_1\Psi_1(\theta_1),$$

which we transform with

$$\Psi_1(\theta_1) = (\sin(k_1\theta_1))^{-1}\psi(\theta_1)$$

to absorb the first order term to give

$$\psi_1''(\theta_1) + \left( \frac{\beta_1}{\cos^2(k_1\theta_1)} + \frac{\ell_2 + \frac{1}{4}(k_1^2 - k_2^2)}{\sin^2(k_1\theta_1)} + k_1^2 - \ell_1 \right) \psi_1(\theta_1) = 0$$

and we make the replacements

$$\beta_1 = k_1^2 \left( \frac{1}{4} - a_1^2 \right), \quad \ell_2 + \frac{1}{4}(k_1^2 - k_2^2) = k_1^2 \left( \frac{1}{4} - A_1^2 \right).$$

On the last slide we had

$$\ell_2 + \frac{1}{4}(\mathbf{k}_1^2 - \mathbf{k}_2^2) = k_1^2 \left( \frac{1}{4} - A_1^2 \right)$$

which along with

$$\frac{k_2^2}{4} - \ell_2 = k_2^2(2n_2 + a_2 + A_2 + 1)^2$$

gives

$$A_1 = \frac{k_2}{k_1}(2n_2 + A_2 + a_2 + 1).$$

Without the  $\frac{1}{4}(\mathbf{k}_1^2 - \mathbf{k}_2^2)$  term, we would have had

$$A_1 = \sqrt{\frac{1}{4} \left( 1 - \frac{k_2^2}{k_1^2} \right) + \frac{k_2^2}{k_1^2} (2n_2 + a_2 + A_2 + 1)^2}.$$

The separate  $\theta_1$  equation becomes

$$\partial_{\theta_1}^2 \psi_1(\theta_1) + \left( \frac{k_1^2 \left( \frac{1}{4} - a_1^2 \right)}{\cos^2(k_1 \theta_1)} + \frac{k_1^2 \left( \frac{1}{4} - A_1^2 \right)}{\sin^2(k_1 \theta_1)} + k_1^2 - \ell_1 \right) \psi_1(\theta_1) = 0$$

where

$$k_1^2 - \ell_1 = \mathbf{k}_1^2 (2\mathbf{n}_1 + \mathbf{A}_1 + \mathbf{a}_1 + 1)^2.$$

and has solutions

$$\Psi_{1,n_1}^{A_1, a_1}(\theta_1) = (\sin(k_1 \theta_1))^{A_1 - \frac{1}{2}} (\cos(k_1 \theta_1))^{a_1 + \frac{1}{2}} P_{n_1}^{(A_1, a_1)}(\cos(2k_1 \theta_1))$$

Finally, the separated radial equation is

$$H\Psi_0(r) = \partial_r^2 \Psi_0(r) + \frac{3}{r} \partial_r \Psi_0(r) + \left( -\omega^2 r^2 + \frac{\ell_1 - \mathbf{k}_1^2 + 1}{r^2} \right) \Psi_0(r) = E \Psi_0(r).$$

We remove the first order terms with the transformation

$$\Psi_0(r) = r^{-\frac{3}{2}} \psi_0(r)$$

to give

$$\partial_r^2 \psi_0(r) + \left( -\omega^2 r^2 + \frac{\frac{1}{4} - \mathbf{k}_1^2 + \ell_1}{r^2} - E \right) \psi_0(r) = 0.$$

Now,

$$u''(x) + \left( -x^2 + \frac{\frac{1}{4} - \mathbf{A}_0^2}{x^2} + 4n + 2A_0 + 2 \right) u(x) = 0$$

has solution

$$u(x) = e^{-\frac{x^2}{2}} x^{A_0 + \frac{1}{2}} L_n^{(A_0)}(x^2),$$

where  $L_n^{(A_0)}(x)$  is a Laguerre function.

We needed

$$A_0^2 = k_1^2 - \ell_1$$

and we already have

$$k_1^2 - \ell_1 = k_1^2(2n_1 + A_1 + a_1 + 1)^2$$

so

$$\Psi_{0,n_0}^{A_0}(r) = e^{-\frac{\omega r^2}{2}} r^{A_0-1} L_{n_0}^{(A_0)}(\omega r^2)$$

where  $L_n^A(x)$  is a Laguerre function and

$$A_0 = k_1(2n_1 + a_1 + A_1 + 1), \quad E = -\omega(4n_0 + 2A_0 + 2).$$

Now, putting these together

$$\begin{aligned} E &= -\omega(4n_0 + 2A_0 + 2) \\ A_0 &= k_1(2n_1 + A_1 + a_1 + 1) \\ A_1 &= \frac{k_2}{k_1}(2n_2 + A_2 + a_2 + 1) \\ A_2 &= \frac{k_3}{k_2}(2n_3 + a_3 + a_4 + 1) \end{aligned}$$

we find

$$E = -2\omega(2n_0 + 2k_1n_1 + 2k_2n_2 + 2k_3n_3 + k_1a_1 + k_2a_2 + k_3a_3 + k_3a_4 + k_1 + k_2 + k_3 + 1)$$

for a solution of the form

$$\Psi_{n_0, n_1, n_2, n_3} = \Psi_{0, n_0}^{A_0}(r) \Psi_{1, n_1}^{A_1, a_1}(\theta_1) \Psi_{2, n_2}^{A_2, a_2}(\theta_2) \Psi_{3, n_3}^{a_3, a_4}(\theta_3).$$

Our aim is to use special function identities to raise and lower the  $n_i$  while preserving  $E$  and produce new operators commuting with  $H$ .

Some examples...

$$K_{0n_0}^{+A_0} = \frac{1-A_0}{r} \partial_r + (2n_0 + A_0 + 1)\omega + \frac{1-A_0^2}{r^2}$$

$$K_{0n_0}^{-A_0} = \frac{1+A_0}{r} \partial_r + (2n_0 + A_0 + 1)\omega + \frac{1-A_0^2}{r^2}$$

These raise and lower  $n_0$  and  $A_0$  simultaneously.

$$K_{0n_0}^{+A_0} \psi_{n_0}^{A_0} = -2(n_0 + 1)(n_0 + A_0) \psi_{n_0+1}^{A_0-2}$$

$$K_{0n_0}^{-A_0} \psi_{n_0}^{A_0} = -2\omega^2 \psi_{n_0-1}^{A_0+2}$$

For the angular functions, we can use Jacobi function identities to make operators that raise and lower  $n$  alone.

$$J_n^+ = -\frac{(N+1)\sin(2k\theta)}{2k}\partial_\theta - \frac{1}{2}\left((N+1)(N+1-c-d)\cos(2k\theta) - (N+1)(c-d) + a^2 - b^2\right)$$

$$J_n^- = \frac{(N-1)\sin(2k\theta)}{2k}\partial_\theta - \frac{1}{2}\left((N-1)(N-1+c+d)\cos(2k\theta) + (N-1)(c-d) + a^2 - b^2\right)$$

$$N = 2n + a + b + 1, \quad \Theta_n^{(a,b)} = \sin^{a+c}(k\theta) \cos^{b+d}(k\theta) P_n^{(a,b)} \cos(2k\theta)$$

$$\begin{aligned} J_n^+ \Theta_n^{(a,b)} &= -2(n+1)(n+a+b+1) \Theta_{n+1}^{(a,b)} \\ J_n^- \Theta_n^{(a,b)} &= -2(n+a)(n+b) \Theta_{n-1}^{(a,b)} \end{aligned}$$

# Raising and lowering operators for TTW solutions

We can also use Jacobi function identities to make operators that raise and lower  $n$  and  $a$  simultaneously.

$$\begin{aligned}K_n^{+a} &= -\frac{(1-a)\cos(k\theta)}{k\sin(k\theta)}\partial_\theta - 2(n(n+a+b+1) + a(a+b)) \\&\quad - (1-a)(a+c+b+d) - \frac{(1-a)(a-c)}{\sin^2(k\theta)} \\K_n^{-a} &= -\frac{(1+a)\cos(k\theta)}{k\sin(k\theta)}\partial_\theta - 2n(n+a+b+1) \\&\quad - (1+a)(a+c+b+d) + \frac{(1+a)(a+c)}{\sin^2(k\theta)}\end{aligned}$$

Again, for

$$\Theta_n^{(a,b)} = \sin^{a+c}(k\theta) \cos^{b+d}(k\theta) P_n^{(a,b)} \cos(2k\theta)$$

we have

$$\begin{aligned}K_n^{+a} \Theta_n^{(a,b)} &= 2(n+1)(n+a) \Theta_{n+1}^{(a-2,b)} \\K_n^{-a} \Theta_n^{(a,b)} &= 2(n+a+b+1)(n+b) \Theta_{n-1}^{(a+2,b)}\end{aligned}$$

For  $k_1 = p_1/q_1$  with  $\gcd(p_1, q_1) = 1$  the operator

$$\Xi_{01}^+ = \underbrace{K_{0\,n_0-(p_1-1)}^{-A_0+2(p_1-1)} \cdots K_{0\,n_0}^{-A_0}}_{p_1 \text{ terms}} \underbrace{J_{1\,n_1+q_1-1}^+ \cdots J_{1\,n_1}^+}_{q_1 \text{ terms}}$$

which has the effect on a basis function of

$$n_0 \rightarrow n_0 - p_1, \quad n_1 \rightarrow n_1 + q_1, \quad A_0 \rightarrow A_0 + 2p_1.$$

and so

$$\begin{aligned} E &= -2\omega(2n_0 + 2k_1 n_1 + \cdots) \rightarrow -2\omega(2(n_0 - p_1) + 2k_1(n_1 + q_1) + \cdots) \\ &= -2\omega(2n_0 + 2k_1 n_1 + \cdots), \end{aligned}$$

that is,  $E$  is unchanged. A similar lowering operator is

$$\Xi_{01}^- = \underbrace{K_{0\,n_0+(p_1-1)}^{+A_0-2(p_1-1)} \cdots K_{0\,n_0}^{+A_0}}_{p_1 \text{ terms}} \underbrace{J_{1\,n_1-(q_1-1)}^- \cdots J_{1\,n_1}^-}_{q_1 \text{ terms}}.$$

This is exactly like the original TTW.

For  $k_2/k_1 = p_2/q_2$  with  $\gcd(p_2, q_2) = 1$  the operator

$$\Xi_{12}^+ = \underbrace{K_{1\,n_1-(p_2-1)}^{-A_1+2(p_2-1)} \cdots K_{1\,n_1}^{-A_1}}_{p_2 \text{ terms}} \underbrace{J_{2\,n_2+q_2-1}^+ \cdots J_{2\,n_2}^+}_{q_2 \text{ terms}}$$

which has the effect on a basis function of

$$n_1 \rightarrow n_1 - p_2, \quad n_2 \rightarrow n_2 + q_2, \quad A_1 \rightarrow A_1 + 2p_2.$$

and so

$$\begin{aligned} E = -2\omega(2n_0 + 2k_1n_1 + 2k_2n_2 + \cdots) &\rightarrow -2\omega(2n_0 + 2k_1(n_1 - p_2) + 2k_2(n_2 + q_2) + \cdots) \\ &= -2\omega(2n_0 + 2k_1n_1 + 2k_2n_2 + \cdots), \end{aligned}$$

that is,  $E$  is unchanged. A similar lowering operator is

$$\Xi_{12}^- = \underbrace{K_{1\,n_1+(p_2-1)}^{+A_1-2(p_2-1)} \cdots K_{1\,n_1}^{+A_1}}_{p_2 \text{ terms}} \underbrace{J_{2\,n_2-(q_2-1)}^- \cdots J_{2\,n_2}^-}_{q_2 \text{ terms}}.$$

The  $K^\pm$  operators differ from the 2D TTW procedure.

The transformation  $n_1 \rightarrow -n_1 - A_1 - a_1 - 1$  while holding  $E$  constant has the effect of changing the sign of  $A_0$ .

Can check that

$$L_{01}^+ = \Xi_{01}^+ + \Xi_{01}^- \quad \text{and} \quad L_{01}^- = \frac{\Xi_{01}^+ - \Xi_{01}^-}{A_0}$$

are polynomials in  $E$ ,  $A_0^2$  and  $A_1^2$ . Since

$$A_0^2 = k_1^2 - \ell_1 \quad \text{and} \quad A_1^2 = \frac{\frac{1}{4}k_2^2 - \ell_2}{k_1^2}$$

we can replace  $E$ ,  $A_0^2$  and  $A_1^2$  with a second order differential operators where ever they appear in these expressions.

E.g. for  $k_1, k_2, k_3 = 2, 1, 1$  these are operators that commute with  $H$  of orders 5 and 6 that are algebraically independent of the second order operators.

For the case  $k_1, k_2, k_3 = 2, 1, 1$ ,  $L_{01}^+$  is a 5<sup>th</sup> order operator.

$$\begin{aligned}
 L_{01}^+ = & \left( -\frac{2}{r^3} \partial_r + \frac{6}{r^4} \right) A_0^2 A_1^2 + \left( -\frac{\cos(4\theta_1)}{2r^3} \partial_r + \frac{\sin(4\theta_1)}{4r^4} \partial_{\theta_1} + \frac{1 + 5 \cos(4\theta_1)}{2r^4} \right) A_0^4 \\
 & + \left( -\frac{1}{r} \partial_r + \frac{2}{r^2} \right) E A_1^2 + \left( \frac{\sin(4\theta_1)}{16} \partial_{\theta_1} + \frac{\cos(4\theta_1)}{4} + \frac{1}{8} \right) E^2 \\
 & + \left( -\frac{\cos(4\theta_1)}{4r} \partial_r + \frac{\sin(4\theta_1)}{4r^2} \partial_{\theta_1} + \frac{3 \cos(4\theta_1) + 1}{2r^2} \right) E A_0^2 + \left( -\frac{10}{r^3} \partial_r + \frac{4}{r^2} \partial_r^2 - \frac{6}{r^4} \right) A_1^2 \\
 & - \left( \frac{\sin(4\theta_1)}{r} \partial_r \partial_{\theta_1} + \frac{3 \cos(4\theta_1) + 2 - a_1^2}{r} \partial_r - \frac{5 \sin(4\theta_1)}{4r^2} \partial_{\theta_1} - \frac{(6 \cos(4\theta_1) + 5 - 4a_1^2)}{2r^2} \right) E \\
 & + \left( -\frac{\sin(4\theta_1)}{4r^2} \partial_r^2 \partial_{\theta_1} + \frac{13 \sin(4\theta_1)}{4r^3} \partial_r \partial_{\theta_1} - \frac{(4 \cos(4\theta_1) + 1)}{2r^2} \partial_r^2 + \frac{13 + 27 \cos(4\theta_1) - 4a_1^2}{2r^3} \partial_r \right. \\
 & \quad \left. - \frac{5 \sin(4\theta_1)}{r^4} \partial_{\theta_1} - \frac{25 \cos(4\theta_1) + 20 - 12a_1^2}{2r^4} \right) A_0^2 \\
 & + \frac{11 \sin(4\theta_1)}{4r^2} \partial_r^2 \partial_{\theta_1} + \frac{(11 - 8a_1^2 + 14 \cos(4\theta_1))}{2r^2} \partial_r^2 - \frac{23 \sin(4\theta_1)}{4r^3} \partial_r \partial_{\theta_1} \\
 & - \frac{26 \cos(4\theta_1) + 23 - 20a_1^2}{2r^3} \partial_r - \frac{21 \sin(4\theta_1)}{4r^4} \partial_{\theta_1} - \frac{3(10 \cos(4\theta_1) + 7 - 4a_1^2)}{2r^4}
 \end{aligned}$$

with the replacements  $E \rightarrow H$ ,  $A_0^2 \rightarrow k_1^2 - L_1$ ,  $A_1^2 \rightarrow (k_2^2 - 4L_2)/(4k_1^2)$ .

We find some polynomially closed subalgebras. For  $i = 1, 2, 3$ , define two differential operators polynomial in their arguments,

$$P_i^{(+)}(L_{i-1}, L_i, A_i^2) = \Xi_i^- \Xi_i^+ + \Xi_i^+ \Xi_i^- \quad \text{and} \quad P_i^{(-)}(L_{i-1}, L_i, A_i^2) = k_i \frac{\Xi_i^+ \Xi_i^- + \Xi_i^- \Xi_i^+}{A_{i-1}}.$$

For each for  $i = 1, 2, 3$  we find,

$$\begin{aligned} [L_i, L_i^-] &= -4k_i^2 q_i^2 L_i^- - 4\alpha_i k_i^2 q_i L_i^+ \\ [L_i, L_i^+] &= 2q_i \{L_i, L_i^-\} - 4k_i^2 q_i L_i^+ + 4k_i^2 q_i^2 L_i^- + 8q_i^3 k_i^2 L_i^- \\ [L_i^+, L_i^-] &= 2q_i (L_i^-)^2 - 2P_i^{(-)}(L_{i-1}, L_i, A_i^2) \end{aligned}$$

and with  $\alpha_1 = 1$ ,  $\alpha_2 = 1/4$  and  $\alpha_3 = 0$ ,

$$\{L_i, L_i^-, L_i^-\} + 2k_i^2 (14q_i^2 - 3\alpha_i) (L_i^-)^2 + 6k_i^2 (L_i^+)^2 + 6k_i^2 q_i \{L_i^+, L_i^-\} - 12k_i^2 P_i^{(+)} + 4k_i^2 q_i P_i^{(-)}$$

Then,

$$[L_j, L_i^\pm] = 0 \text{ for } i \neq j \quad \text{and} \quad [L_j^\pm, L_i^\pm] = [L_j^\pm, L_i^\mp] = 0 \text{ for } |i - j| > 1,$$

whereas  $[L_i^\pm, L_{i+1}^\pm]$  and  $[L_i^\pm, L_{i+1}^\mp]$  are related to the other symmetries by polynomial identities.

The TTW system can be extended to higher dimensions and leads to superintegrable systems in non-conformally-flat spaces.

One possible extension was presented here and required a conformally covariant deformation of the potential in order to use the raising and lowering operator method to prove superintegrability.

This suggests a ‘natural’ differential operator associated with a (conformal-) Killing tensor that commutes with a conformally covariant Laplacian other than the usual conformally covariant Laplacian  $\nabla^2 - \mathcal{R}/6$ .