"[Moduli spaces] have also appeared in theoretical physics like string theory: many computations of path integrals are reduced to integrals of Chern classes on such moduli spaces."

Shing-Tung Yau

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Phants and Surfaces

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The moduli space $\mathcal{M}(S)$ of a surface S of genus g and with n punctures is:

{equivalence classes of Riemann surfaces homeomorphic to S}

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How can we study it?

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The moduli space $\mathcal{M}(S)$ of a surface S of genus g and with n punctures is:

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How can we study it?

- build every Riemann surface.
- identify biholomorphic ones.

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The anatomy of a Riemann surface:

• A Riemann surface $R \Rightarrow$ a unique hyperbolic surface R_h .



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- ► Simple loops on hyperbolic surfaces ⇒ unique geodesics.



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- A Riemann surface $R \Rightarrow$ a unique hyperbolic surface R_h .
- ► Simple loops on hyperbolic surfaces ⇒ unique geodesics.
- Cut along these geodesics \Rightarrow hyperbolic pairs of pants.



So, how can we generate every Riemann surface?

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- So, how can we generate every Riemann surface?
 - There's a unique pair of pants for any three boundary lengths.

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- Can vary these lengths, and

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- vary the gluing.



Teichmüller space

Take geodesics $\{\gamma_1, \ldots, \gamma_{3g-3+n}\}$ that decompose R_h into pairs of pants. For each γ_i , we have:

- \mathbb{R}^+ possible lengths ℓ_i , and
- \mathbb{R} possible twists τ_i (keep track of some winding number)

Teichmüller space

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- \mathbb{R}^+ possible lengths ℓ_i , and
- \mathbb{R} possible twists τ_i (keep track of some winding number) We get the Teichmüller space

$$\mathcal{T}(S) = (\mathbb{R}_+ \times \mathbb{R})^{3g-3+n}.$$

The same hyperbolic surface appears infinitely many times in Teichmüller space, and the identification map

$$\mathcal{T}(S)
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comes from a group action.

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The Weil-Petersson 2-form

$$\Omega_{WP} := \mathrm{d}\ell_1 \wedge \mathrm{d}\tau_1 + \ldots + \mathrm{d}\ell_{3g-3+n} \wedge \mathrm{d}\tau_{3g-3+n}$$

is invariant under this group action, and makes $\mathcal{M}(S)$ a symplectic manifold.

Tweaking the boundary

Instead of uniformizing to have cusps at the punctures, we can ask for geodesics with specified boundary lengths $\vec{L} = (L_1, \ldots, L_n)$.

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- The volume of M(S) for Ω_W(L)^(3g-3+n) is a rational polynomial in π² and L²_i!
- Shove the coefficients in a generating function and exponentiate to get a solution to the KdV equations!

What happens if we specify cone-angles at the punctures instead?



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What happens if we specify cone-angles at the punctures instead?



Up to cone-angle π , everything we've talked about still holds true.

What happens between π and 2π ?

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What happens between π and 2π ?

We lose (unique) geodesic representatives.

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To fix this: *push past* the cone-point.

When cutting surface along given broken geodesics, extend (and sometimes retract) our surface to obtain *phantom pants* or *phants* with geodesic boundary.



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Our phants coordinates are very representation theoretic, so these coordinates will produce the "correct" Weil-Petersson form.

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