

# Random rectangle-triangle tilings and Painlevé VI

Jan de Gier

University of Melbourne

ANZAMP inaugural meeting  
Lorne, 4 December 2012

Based on ideas of:

Rick Kenyon

Bernard Nienhuis

Andrei Okounkov

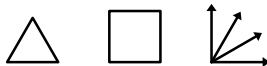
Paul Zinn-Justin

## Rectangle-triangle random tilings

Random tilings of triangles and rectangles with long side  $\ell$ .

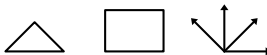
- Square Triangle

$\ell = 1$ , 12-fold.



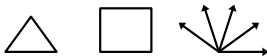
- Rectangle Triangle

$\ell = \sqrt{2}$ , 8-fold.

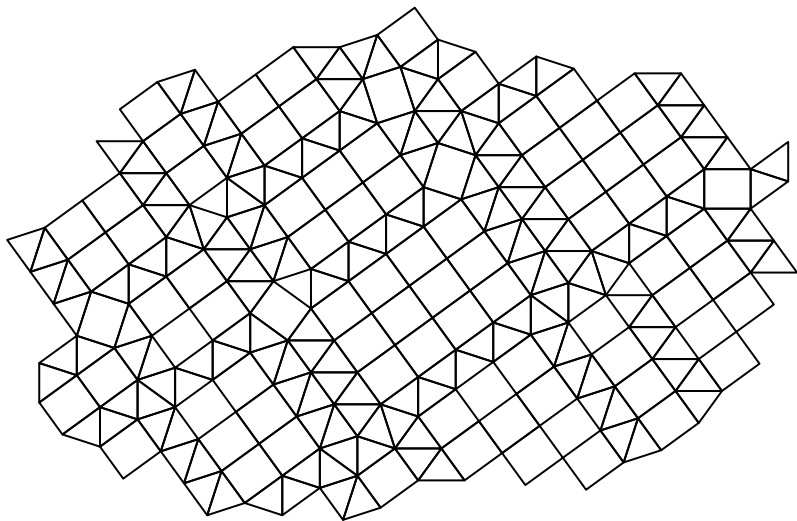


- Rectangle Triangle

$\ell = 2 \cos \frac{3\pi}{10}$ , 10-fold.



# 10-fold rectangle triangle tiling



## Transfer matrix $T$

$T$  generates ensemble of tilings by adding a new row of tiles.

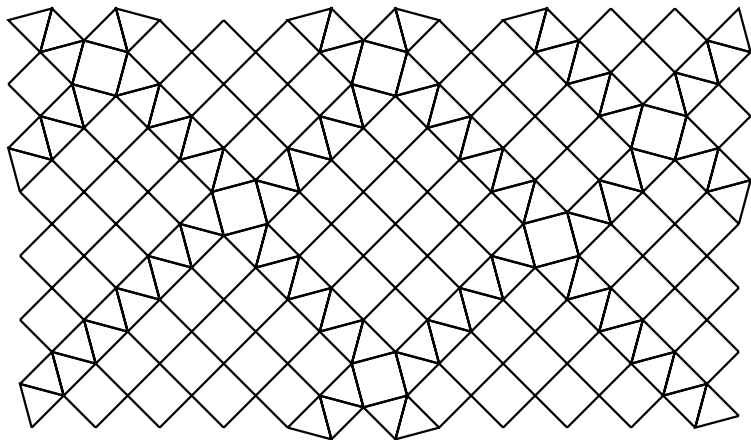
The partition sum

$$Z = \text{Tr} T^N = \sum_i \Lambda_i^N,$$

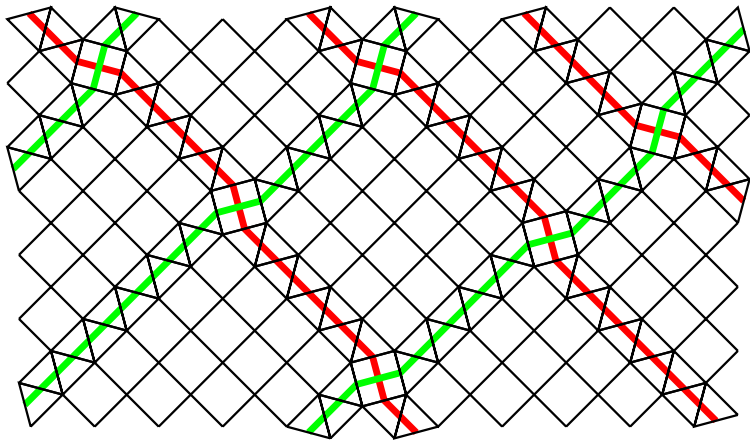
is related to the entropy

$$\sigma = \frac{1}{N} \log Z \sim \log \Lambda_{\max}$$

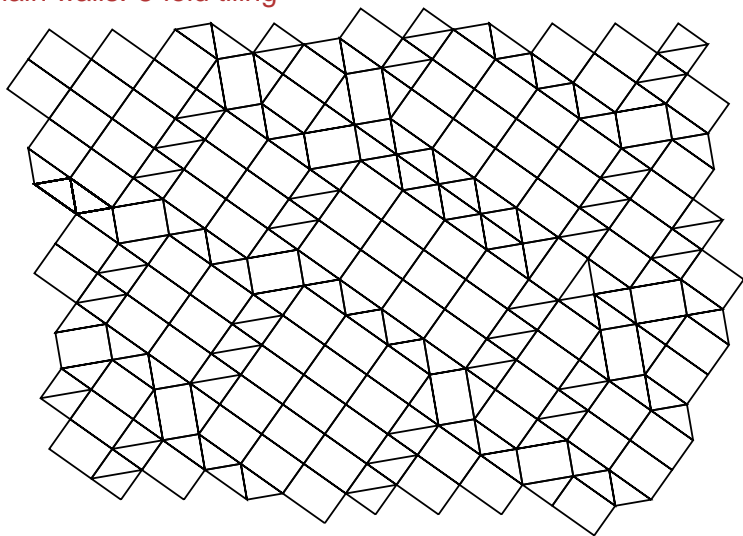
## Domain walls: 12-fold tiling



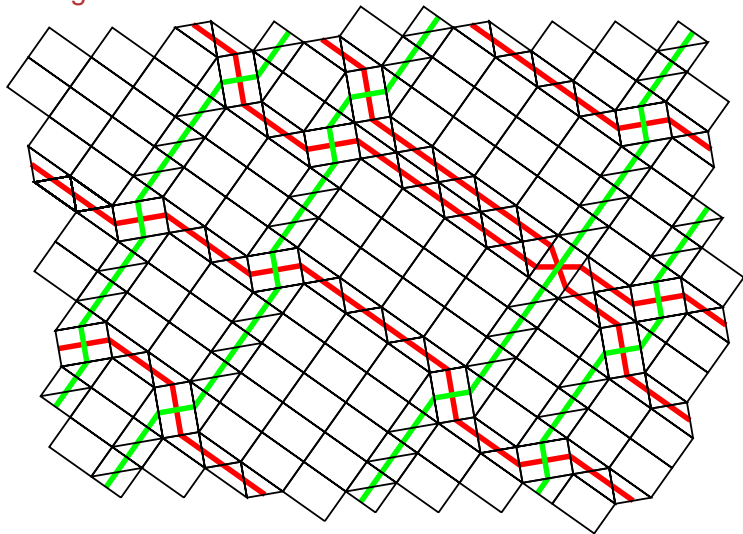
## Domain walls: 12-fold tiling



## Domain walls: 8-fold tiling

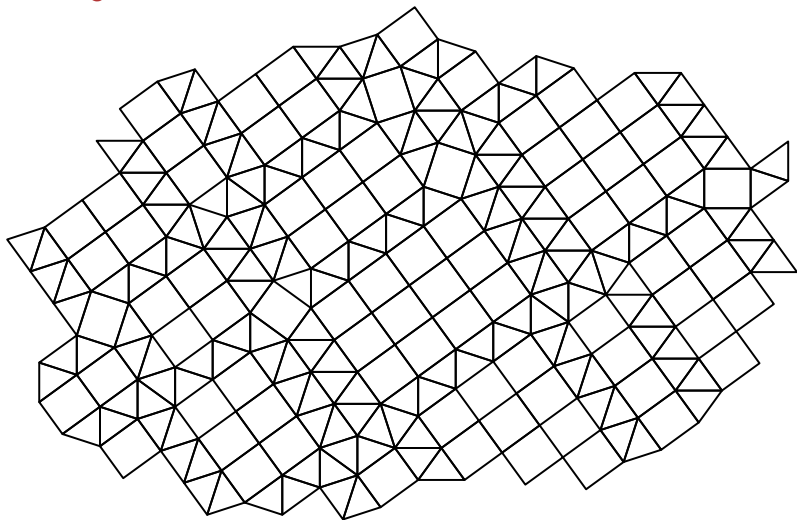


## 8-fold tiling

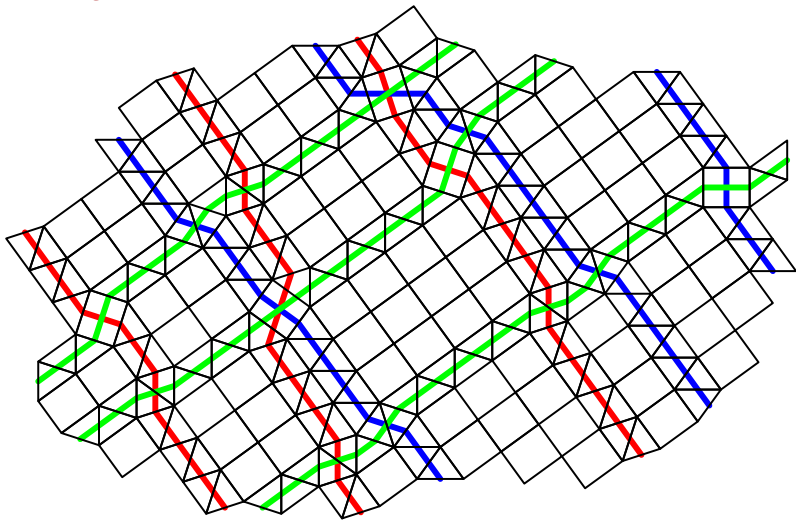




## 10-fold tiling



## 10-fold tiling



# Bethe ansatz

- Domain walls are interpreted as “world lines” of particles
- The transfer matrix is the evolution operator
- It can be diagonalised using a plane wave ansatz

The solution of the eigenvalue problem has the following form

$$\Lambda = \left( \prod_{i=1}^n u_i^{-1} + 1 \right) \prod_{j=1}^m v_j,$$

$$u_i^N = (-1)^{n-1} \prod_{j=1}^m \frac{1}{u_i - v_j},$$

$$1 = (-1)^{m-1} \prod_{i=1}^n \frac{1}{u_i - v_j},$$

## Solution: 10-fold

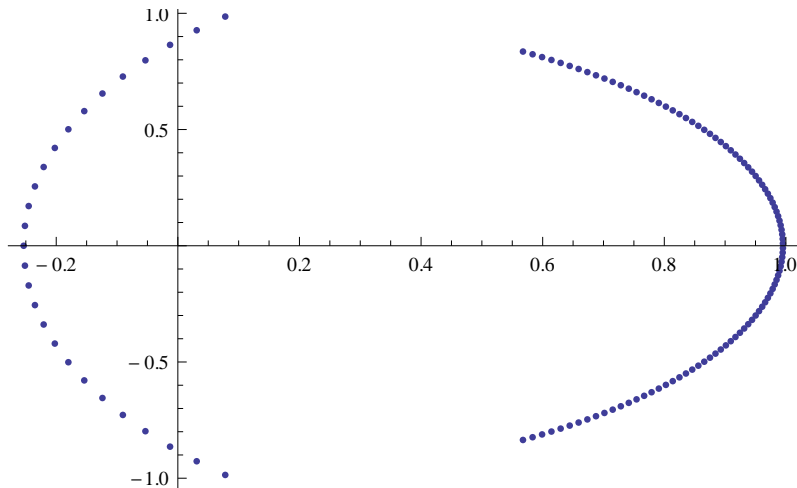
$$\Lambda = \prod_{i=1}^n u_i \prod_{j=1}^m v_j,$$

$$u_i^N = (-)^{n-1} \prod_{j=1}^m (u_i - v_j) \prod_{l=1}^{n_2} (w_l + u_i - u_i^{-1}),$$

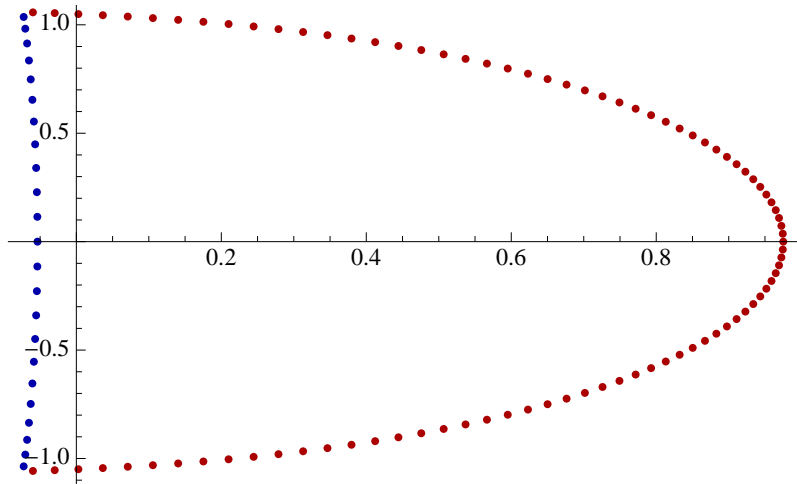
$$v_j^N = (-)^{m-1} \prod_{i=1}^n (u_i - v_j),$$

$$(-)^{n_2} = \prod_{i=1}^n (w_l + u_i - u_i^{-1}).$$

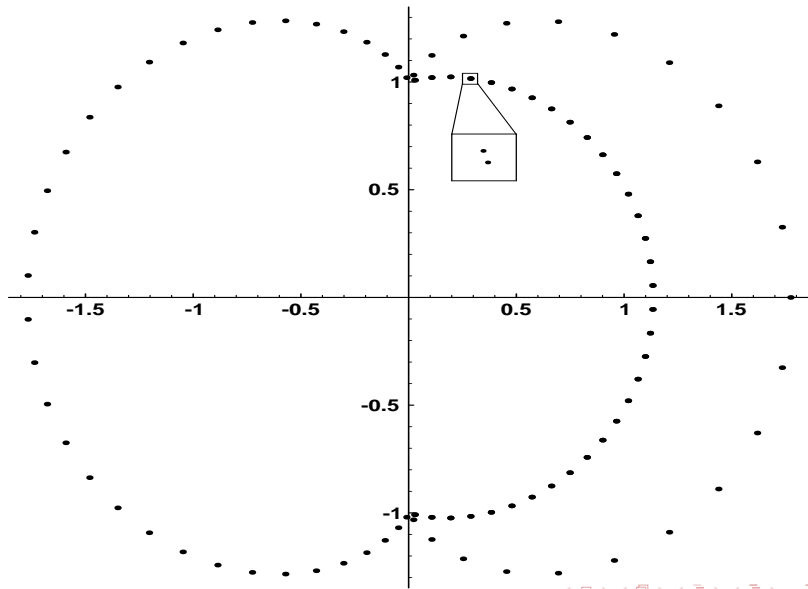
## Numerical solution: 12-fold



## Numerical solution: 12-fold



## Numerical solution: 10-fold



## Logarithmic form

Bethe ansatz in logarithmic form:

$$F_1(u) = \log u + \frac{1}{N} \sum_{j=1}^{M_2} \log(u - v_j),$$

$$F_2(v) = \frac{1}{N} \sum_{i=1}^{M_1} \log(u_i - v).$$

$$F_1(u_i) = 2\pi i\mathbb{Z} \quad F_2(v_j) = 2\pi i\mathbb{Z} \quad \text{for all } i \text{ and } j.$$



## Logarithmic form

Bethe ansatz in logarithmic form:

$$F_1(u) = \log u + \frac{1}{N} \sum_{j=1}^{M_2} \log(u - v_j),$$

$$F_2(v) = \frac{1}{N} \sum_{i=1}^{M_1} \log(u_i - v).$$

$$F_1(u_i) = 2\pi i \mathbb{Z} \quad F_2(v_j) = 2\pi i \mathbb{Z} \quad \text{for all } i \text{ and } j.$$

In the thermodynamic limit ( $N \rightarrow \infty$ ) the Bethe ansatz equations imply the following integral equations for the root densities  $f_i(u) := F'_i(u)$ :

---


$$f_1(u) = \frac{1}{u} - \frac{1}{2\pi i} \int_v \frac{f_2(v)}{v - u} dv, \quad f_2(v) = -\frac{1}{2\pi i} \int_u \frac{f_1(u)}{u - v} du.$$


---

$$f_1(u) = \frac{1}{u} - \frac{1}{2\pi i} \int_v \frac{f_2(v)}{v-u} dv,$$
$$f_2(v) = -\frac{1}{2\pi i} \int_u \frac{f_1(u)}{u-v} du.$$

These equations are difficult to solve in generality.

$$f_1(u) = \frac{1}{u} - \frac{1}{2\pi i} \int_v \frac{f_2(v)}{v-u} dv,$$
$$f_2(v) = -\frac{1}{2\pi i} \int_u \frac{f_1(u)}{u-v} du.$$

These equations are difficult to solve in generality.

We can show that  $f_1$  and  $f_2$  satisfy a system of first order linear differential equations.

$$f_1(u) = \frac{1}{u} - \frac{1}{2\pi i} \int_v \frac{f_2(v)}{v-u} dv,$$

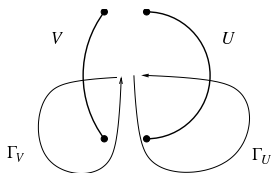
$$f_2(v) = -\frac{1}{2\pi i} \int_u \frac{f_1(u)}{u-v} du.$$

These equations are difficult to solve in generality.

We can show that  $f_1$  and  $f_2$  satisfy a system of first order linear differential equations.

The theory of isomonodromic transformations allows us to determine the exact form of this system, which we can then hope to solve using expansion and/or perturbation techniques.

# Monodromy



$$f_1(u) = \frac{1}{u} - \frac{1}{2\pi i} \int_V \frac{f_2(v)}{v-u} dv,$$

$$f_2(v) = -\frac{1}{2\pi i} \int_U \frac{f_1(u)}{u-v} du.$$

$$G(z) = a_1 f_1(z) + a_2 f_2(z),$$

The analytic continuation along paths  $\Gamma_V$  and  $\Gamma_U$  crossing the curves  $U$  and  $V$  can be summarised with the following monodromy matrices:

$$\Gamma_U : \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \mapsto \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \quad \Gamma_V : \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \mapsto \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}.$$

## Differential equation

Note that  $(f_1, f_2)$  satisfies a Riemann-Hilbert problem (RHP) with constant matrices

$$M_V = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \quad M_U = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}.$$

Let

$$Y = \begin{pmatrix} f_1 & f_2 \\ \tilde{f}_1 & \tilde{f}_2 \end{pmatrix},$$

be a matrix solution. After traversing a path  $\gamma$ ,  $Y(z)$  has changed to  $Y(z_\gamma)$  and we have

$$Y(z_\gamma) = Y(z)M_\gamma,$$

where  $M_\gamma$  is the monodromy matrix corresponding to  $\gamma$ .

## Differential equation

$$Y(z_\gamma) = Y(z)M_\gamma,$$

implies that

$$Y'(z_\gamma)Y(z_\gamma)^{-1} = Y'(z)Y(z)^{-1},$$

is monodromy free, and therefore meromorphic around  $z$ . So we can write

$$\frac{\partial}{\partial z} Y(z) = A(z)Y(z),$$

where  $A(z)$  is analytic everywhere except possibly at the endpoints.

## Differential equation

$$Y(z_\gamma) = Y(z)M_\gamma,$$

implies that

$$Y'(z_\gamma)Y(z_\gamma)^{-1} = Y'(z)Y(z)^{-1},$$

is monodromy free, and therefore meromorphic around  $z$ . So we can write

$$\frac{\partial}{\partial z} Y(z) = A(z)Y(z),$$

where  $A(z)$  is analytic everywhere except possibly at the endpoints.

We will assume that  $A(z)$  has only simple poles at the endpoints:

$$A(z) = \sum_{i=1}^4 \frac{A_i}{z - b_i}.$$

The question is: What are the matrices  $A_i$  for our problem?



## Differential equation

Because infinity is monodromy free we have

$$\sum_{i=1}^4 A_i = 0,$$

## Differential equation

Because infinity is monodromy free we have

$$\sum_{i=1}^4 A_i = 0,$$

Note that due to the specific form of the monodromy, the matrices  $A_i$  will not be diagonalisable.

## Isomonodromic deformations

In the general the solution  $Y(z)$  of

$$\frac{\partial}{\partial z} Y(z) = A(z) Y(z),$$

will depend on all the parameters  $b_i$ ,  $i = 1, \dots, 4$ .

## Isomonodromic deformations

In the general the solution  $Y(z)$  of

$$\frac{\partial}{\partial z} Y(z) = A(z) Y(z),$$

will depend on all the parameters  $b_i$ ,  $i = 1, \dots, 4$ .

The matrices  $A_i = A_i(b)$  will have to depend on  $b$  as well, and must satisfy the following consistency conditions:

$$\begin{aligned} \frac{\partial}{\partial z} Y(z, b) &= \sum_{i=1}^4 \frac{A_i(b)}{z - b_i} Y(z, b), \\ \frac{\partial}{\partial b_i} Y(z, b) &= -\frac{A_i(b)}{z - b_i} Y(z, b), \quad (i = 1, \dots, 4). \end{aligned}$$

## Painlevé VI

Equivalently, we require the Schlesinger equations

$$\begin{aligned}\frac{\partial}{\partial b_j} A_i(b) &= \frac{[A_j, A_i]}{b_j - b_i} \quad (j \neq i), \\ \frac{\partial}{\partial b_i} A_i(b) &= - \sum_{j \neq i} \frac{[A_j, A_i]}{b_j - b_i}.\end{aligned}$$

Sending  $b_1, b_2, b_3$  and  $b_4$  to  $0, 1, t, \infty$ , these equations imply Painlevé VI:

$$\begin{aligned}- \frac{(f-1)f(f-t)}{2(t-1)^2 t^2} \left( 1 + \frac{t(t-1)}{(f-t)^2} \right) - \frac{1}{2} \dot{f}^2 \left( \frac{1}{f-t} + \frac{1}{f} + \frac{1}{f-1} \right) \\ + \dot{f} \left( \frac{1}{f-t} + \frac{1}{t} + \frac{1}{t-1} \right) + \ddot{f} = 0\end{aligned}$$

where  $f = f(A_0, A_1)$ .

## Conclusion

- Bethe ansatz for random tilings  $\Rightarrow$  matrix Riemann-Hilbert problem
- Find isomonodromic deformation
- Leads to differential equation with parameter given by Painlevé VI.
- General solution?